



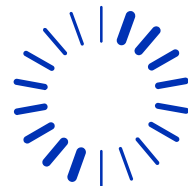
Fluxgate Virtual Sensor

Atef LEKDIM
10/26/2023

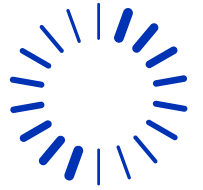


Agenda

- Introduction
- Model Builder
- Livelink with Matlab
- Results
- Conclusion






Introduction




- All applications that require high precision


Automotive:

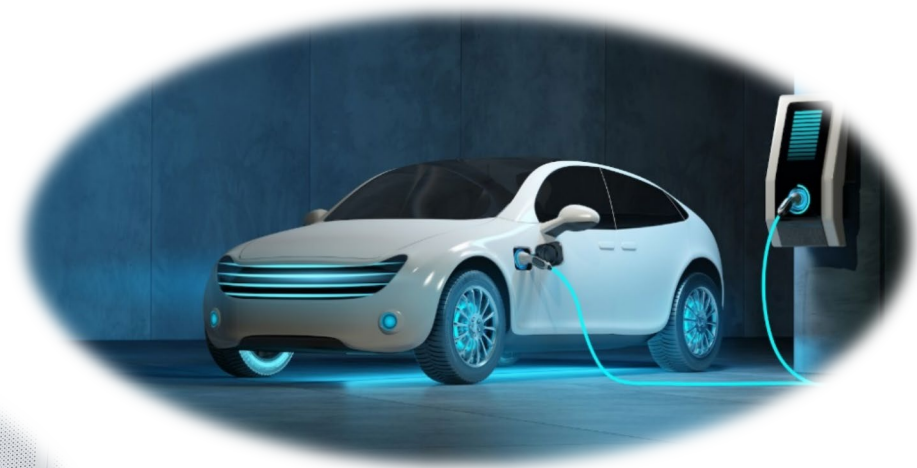
- RCDs for On/Out Board Chargers (CDTs , CDSR )
- Battery management systems (CABs )

Health equipments:

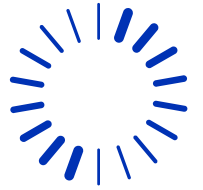
- MRI scanners (ITL , ...)

Renewable energies:

- Solar energy (, ...)
- Others



Model Builder



- Magnetic field physic

- Component 1 (comp 1)
 - Definitions
 - Géométrie 1
 - Materials
 - Champs magnétiques (mf)**
 - Electrical Circuit (cir)
 - Events (ev)
 - General Form PDE (g)
 - Meshes
- Study 1
 - Step 1: Coil Geometry Analysis
 - Step 2: Time Dependent
 - Solver Configurations
 - Results

Anisotropy included along the radius

Coordinate System Selection

Coordinate system:
Cylindrical System 2 (sys2)

Constitutive Relation B-H

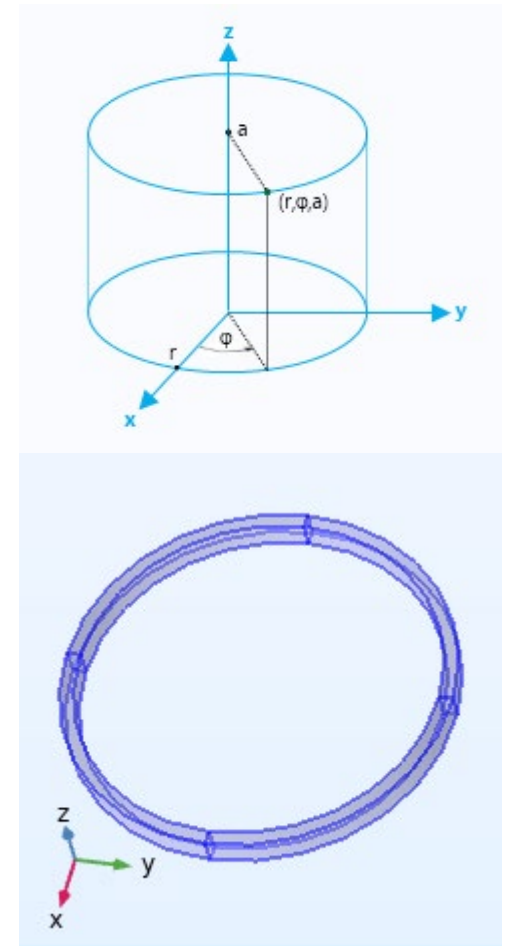
Magnetization model:
Relative permeability

$\mathbf{B} = \mu_0 \mu_r \mathbf{H}$

Relative permeability:
 μ_r User defined

5	0	0
0	MuZ(abs(-mf.Bx*sin(sys2....	0
0	0	MuZ(abs(-mf.Bx*sin(sys2....

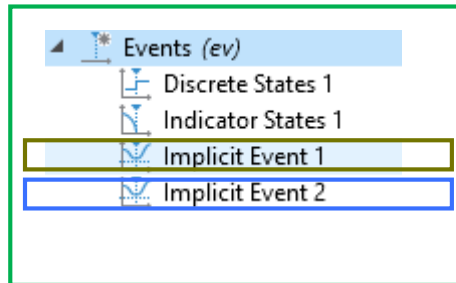
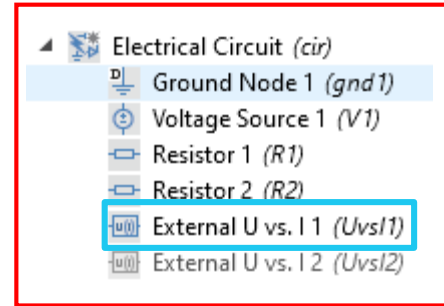
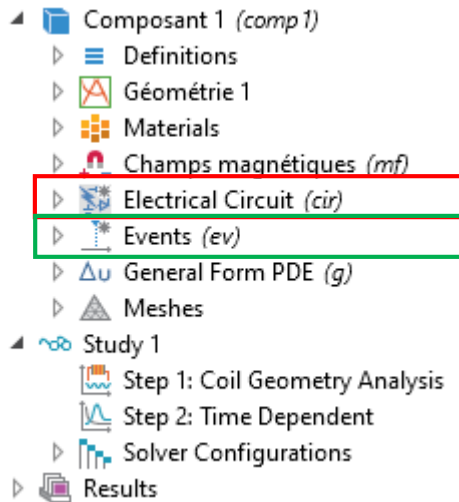
Diagonal



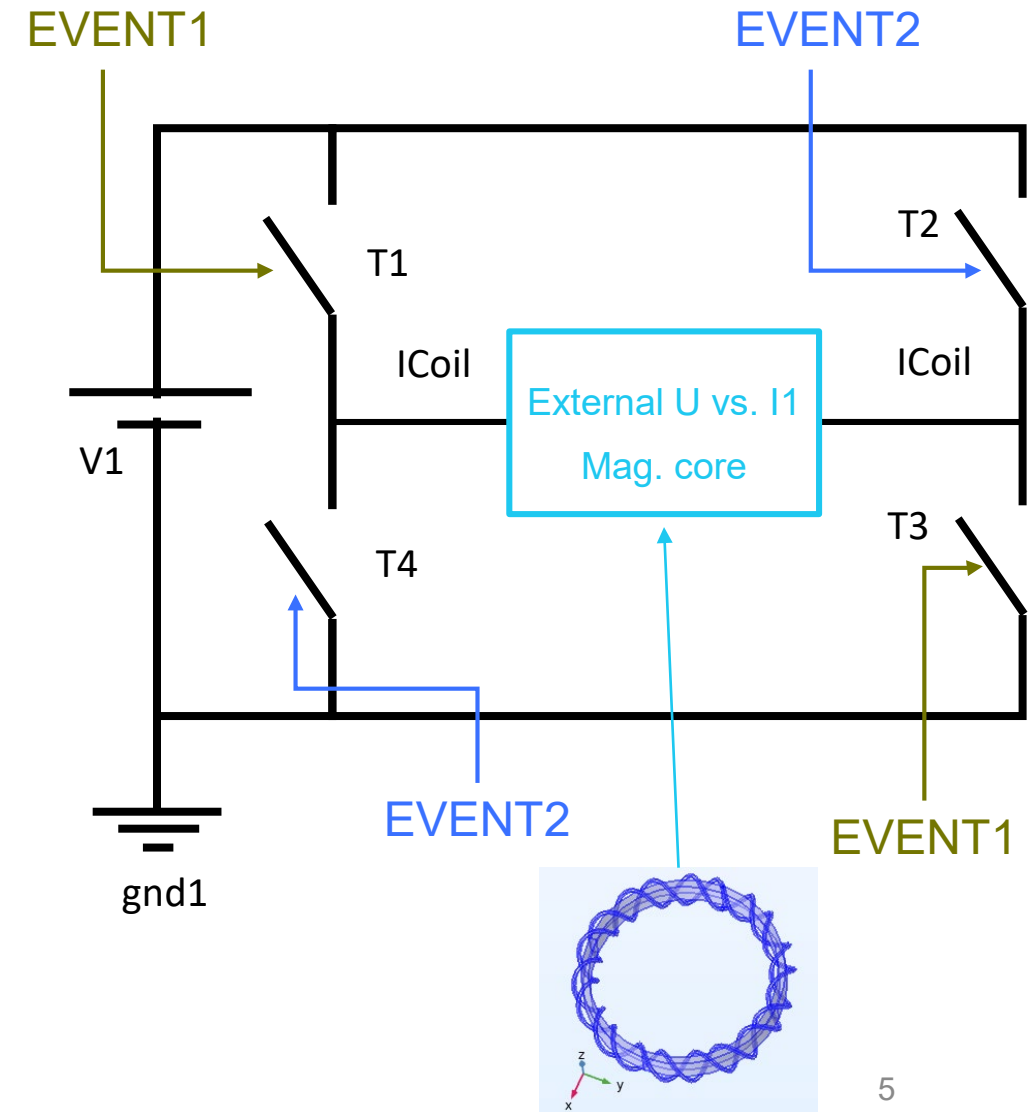
Model Builder



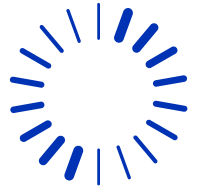
- Electrical circuit and Events modules
 - Saturate the magnetic material both sides (fluxgate principle)



Control of transistors



Model Builder



- General Form PDE module

- Composant 1 (comp1)
 - Definitions
 - Géométrie 1
 - Materials
 - Champs magnétiques (mf)
 - Electrical Circuit (cir)
 - Events (ev)
 - General Form PDE (g)**
 - Meshes
- Study 1
 - Step 1: Coil Geometry Analysis
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Settings
General Form PDE

Label: General Form PDE 1

Domain Selection

Override and Contribution

Equation

$$e_a \frac{\partial^2 \mathbf{u}}{\partial t^2} + d_a \frac{\partial \mathbf{u}}{\partial t} + \nabla \cdot \Gamma = f$$
$$\mathbf{u} = [H_{dynx}, H_{dyny}, H_{dynz}]^T$$
$$\nabla = \left[\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right]$$

Conservative Flux

Source Term

$H_{dynx} - mf.Hx - \gamma * d(mf.Bx, t)$ A/m

f $H_{dyny} - mf.Hy - \gamma * d(mf.By, t)$ A/m

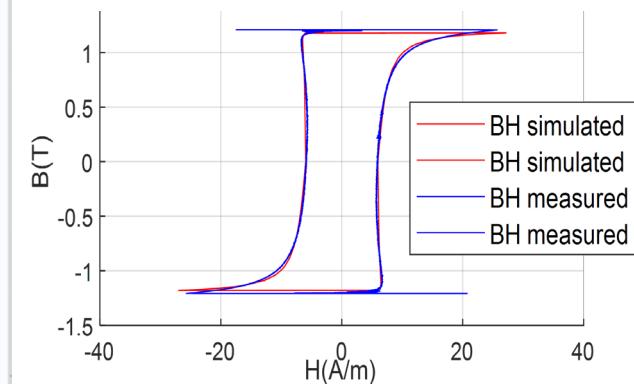
$H_{dynz} - mf.Hz - \gamma * d(mf.Bz, t)$ A/m

Damping or Mass Coefficient

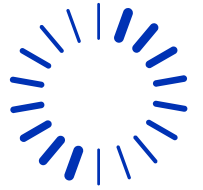
Mass Coefficient

Basic magnetic model

$$H_{dyn}(B) = H_{stat}(B) + \gamma \times \frac{dB}{dt}$$



LiveLink with Matlab



- Basic livelink Matlab script steps

- Loading the COMSOL model

- Matlab main loop

- Setting model parameters

- Run the simulation

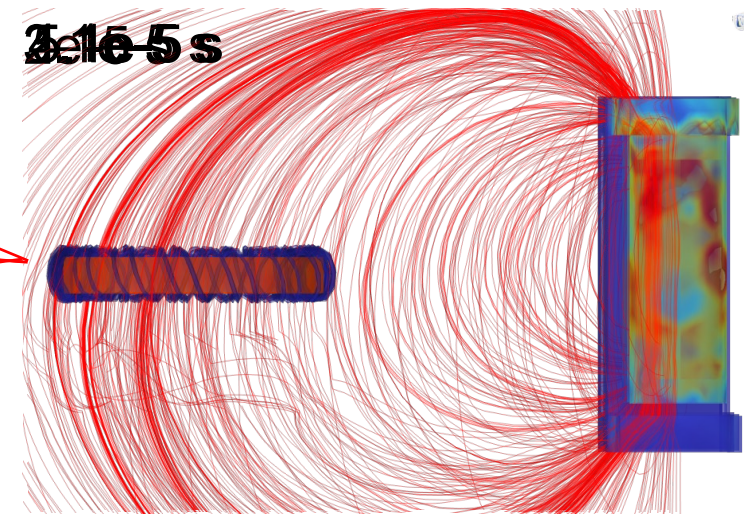
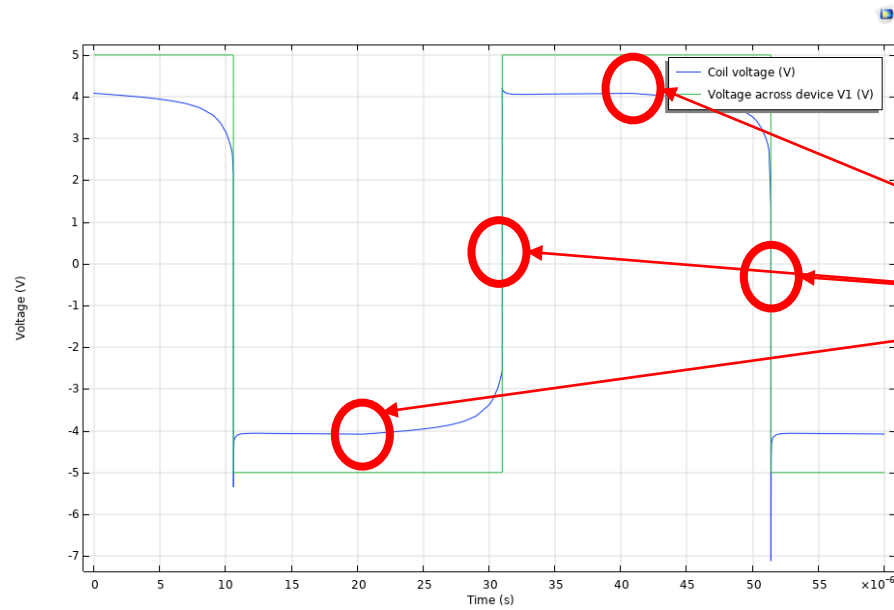
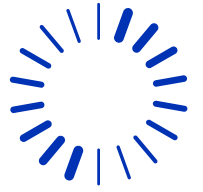
- Extraction of simulation data

- Post processing

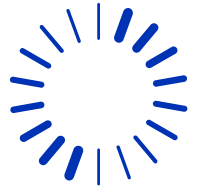
```
Virtual_fluxgate_sensor.m x +
32
33 %*****loading of the COMSOL model*****
34 model=mphopen('Virtual_fluxgate_sensor');
35 %mphlaunch(model)
36 i=1;ii=1;iii=1;
37 for ii=1:length(Ileak)
38 for iii=1:length(ANGLE)
39 for i=1:length(I1)
40 %*****setting of the parameters*****
45 model.param.set('Ileak', [num2str(Ileak(ii)) '[A]']);
46 model.param.set('Irelay_0', [num2str(Irelay_0) '[A]']);
47 model.param.set('ANGLE', [num2str(ANGLE(iii)) '[A]']);
48 model.param.set('I1', [num2str(I1(i)) '[A]']);
49 model.param.set('I2', [num2str(I2(i)) '[A]']);
50 model.param.set('I3', [num2str(I3(i)) '[A]']);
51 % model.param.set('I0', [num2str(I0) '[A]']);
52 model.param.set('Ns', [num2str(Ns) '[1]']);
53 % model.param.set('gamma', [num2str(gamma) '[1]']);
57 figure
58 mphgeom(model,'geom1','facealpha',0.5)
59 %*****Run COMSOL Model *****
60 model.result.table('tbl2').clearTableData
61 tic
62 model.study('std1').run
63 temps simul(i,1)=toc/60
64 % %*****COMSOL data extraction*****
70 MMM=mphtable(model,'tbl2');
71 MM=MMM.data;
72 %model.result.table('tbl2').save([PathName,'With all shieldings Ileak=',num2s
73 figure
74 mphplot(model,'pg36','rangenum',12)
75 %*****Sensor measurements*****
76 Measurements(:,iii+(ii-1)*2)=Sensor_PostProcess_function(MM,Long_moy,Cross_Se
77 %save(strcat(PathName,strtok('Extraction parametres tripahse Ileak0A With all
78 clear MMM MM
79 end
80 end
81 end
```

Results

- Results over simulation time

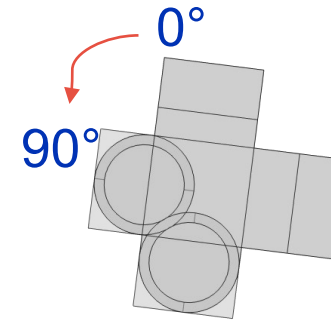
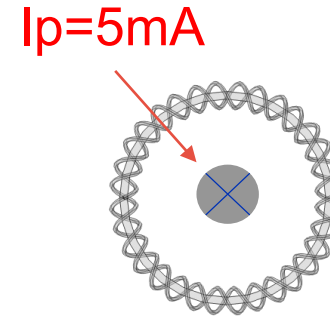
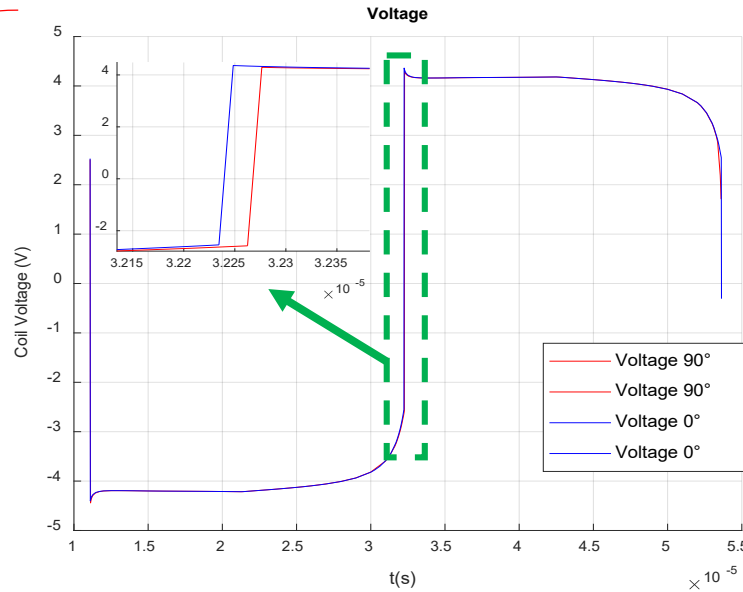


Results



- Sensor electrical results with respect to relay orientation

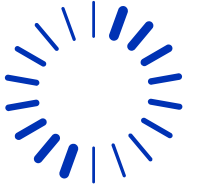
Matlab Post Processing results



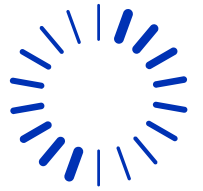
Channels	Ref (relay off)	0° rot.	90° rot.	0° error (%)	90° error(%)
Analog	0.00351	0.00358	0.00356	+1.8	+1.3
Digital	0.00296	0.00263	0.00198	-11	-33.3

The digital channel is highly sensitive to electromagnetic pollutions

Conclusion



- The realised virtual sensor is useful for
 - continuous improvement,
 - simulating extreme conditions that can't be easily set in real life,
 - simulating customer environment for better integration of the sensor
- Next steps
 - External material DLL model (issue with time-stepping implementation)
 - Application builder



Thank you for your attention
Q&A